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# The *In Situ* Rock Thin Section Instrument for Space Exploration

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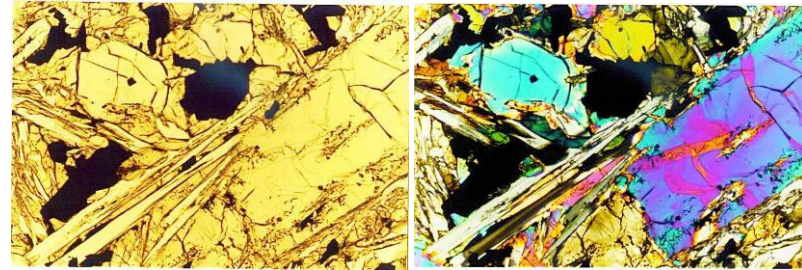
# Team and History

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- CSM 2005 Senior Design Project initiated by Mike Duke
- PIDDP 2006-2009 CSM and Honeybee Robotics
- R. C. Anderson, JPL – developed a TRL 3 thin section device on JPL RTD funding
- NOW  
CSM, Honeybee and JPL (Anderson) working together to take it to the next level

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- Why rock thin sections?

A powerful tool for understanding the origin and evolution of rocks.



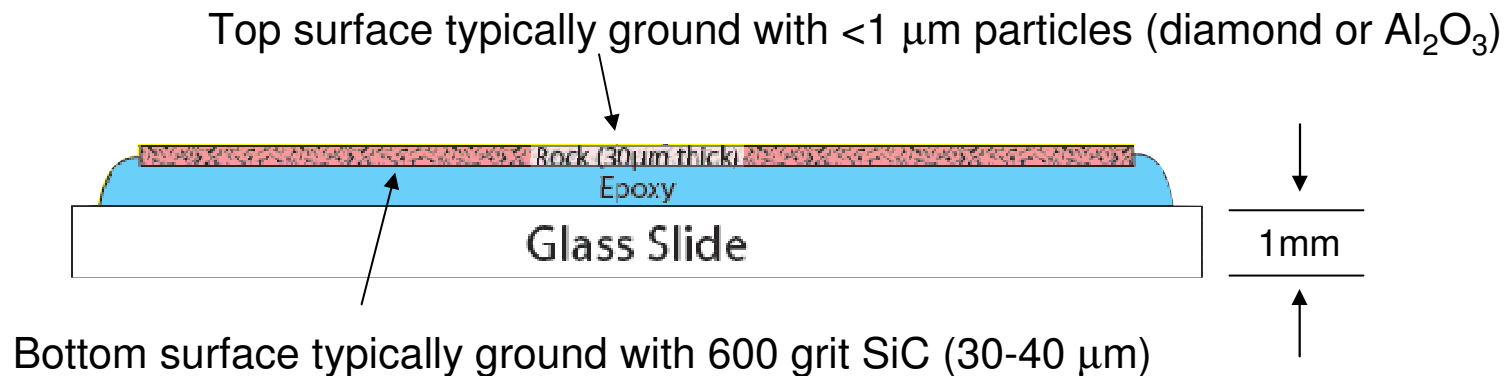
Apollo 12 Lunar Basalt – reflected light and cross polarizer transmitted light

- Thin Sections are ubiquitous in geological sciences and engineering

Used to identify minerals, size, shape, weathering, voids, associations...

For Use in Space Resources – **Prospecting Tool**

# What is a thin section? (Polished Thin Section)



## Key attributes

1. 30  $\mu\text{m}$  thick
2. Flat – varies by  $<< 30$  microns
3. Polished surfaces
  - Top  $< 0.2\ \mu\text{m}$  Ra
  - Bottom  $\sim 1\ \mu\text{m}$  Ra

# Terrestrial Labs



**Step 1.** Selecting an appropriate rock specimen.



**Step 2.** Cutting of a rock to an appropriate shape and size: a tablet ~26mm wide x 46mm long x 5mm thick.



**Step 3.** Grinding the tablets' 26mmx46mm surface to remove any saw or wire cutter marks



**Step 4.** Epoxy the rock tablet ground surface to a glass slide



**Step 5.** Grinding the tablets top (free) surface it to a required thickness (~30 micron), polishing it to a required surface roughness (0.1 micron)



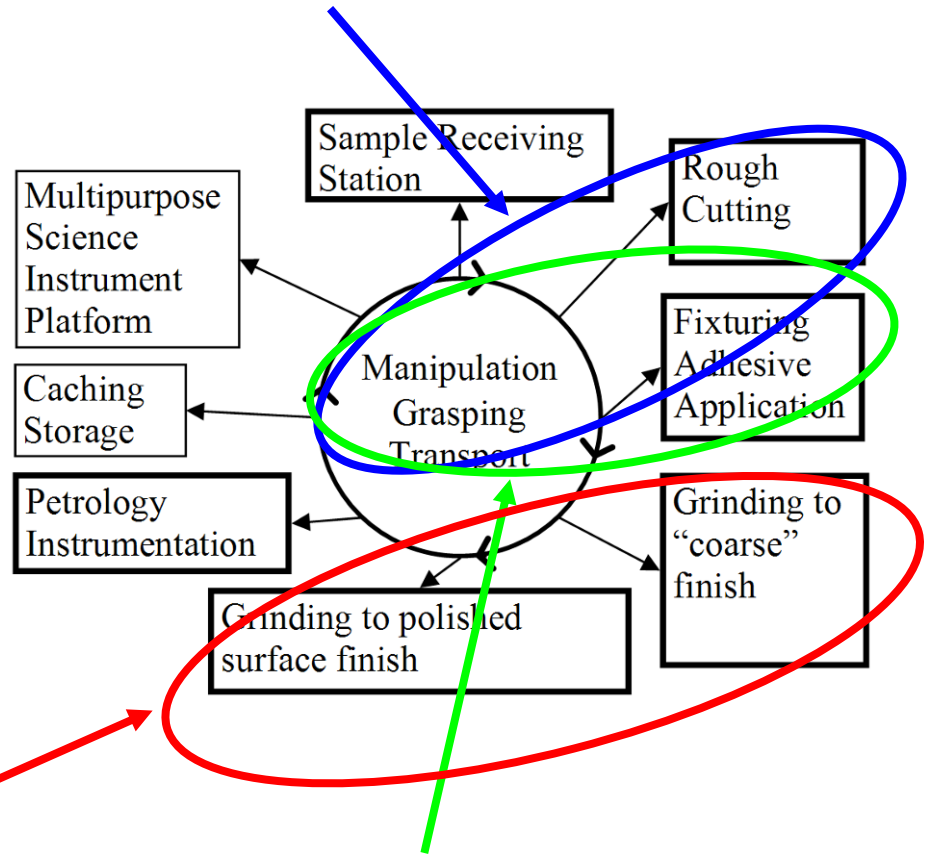
**Step 6.** Viewing the thin section under reflected and transmitted light

# Take it to Space

## Major Hurdles

- Cutting of an irregular sample to a workable size and shape
- Fixturing of the sample
- Grinding and polishing of cut sample to finished thin section.
- Reduction or elimination of consumables normally used.
- All grinding, cutting and polishing to be done DRY
- Reduce and measure wear of surfaces

## CSM: Diamond Wire Saw



Honeybee Robotics:  
GRITS System

JPL: ISPAD Epoxy/Slide  
approach and sample  
handling expertise

# Rough cutting

## Diamond Wire vs. Cutting Wheel for Tablet Generation

### Diamond Wire Pros:

- Small Cut Volume (kerf) → reduced dust generation and thermal stress
- Low applied cutting force → reduce gripping requirements, lower power
- Flat and smooth surface
- Cut orthogonal planes

### Diamond Wire Cons:

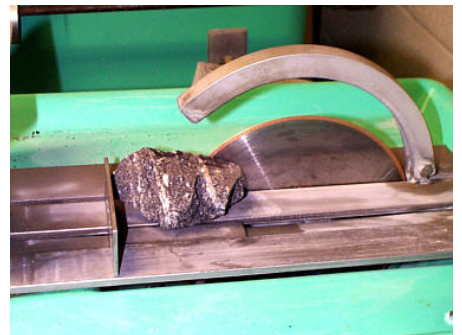
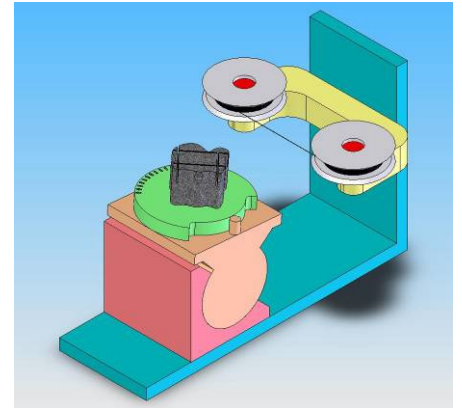
- Requires instrumentation to control cutting.
- Possibility of wire breakage

### Cutting Wheel Pros:

- Higher total volume of cutting media.
- Simpler control (only contact force required)

### Cutting Wheel Cons:

- Higher power requirements.
- Larger kerf → more dust generation, more heating during cutting.
- Requires more degrees-of-freedom to cut in multiple planes, relative to wire.
- Wheel diameter determines size of sample that can be cut

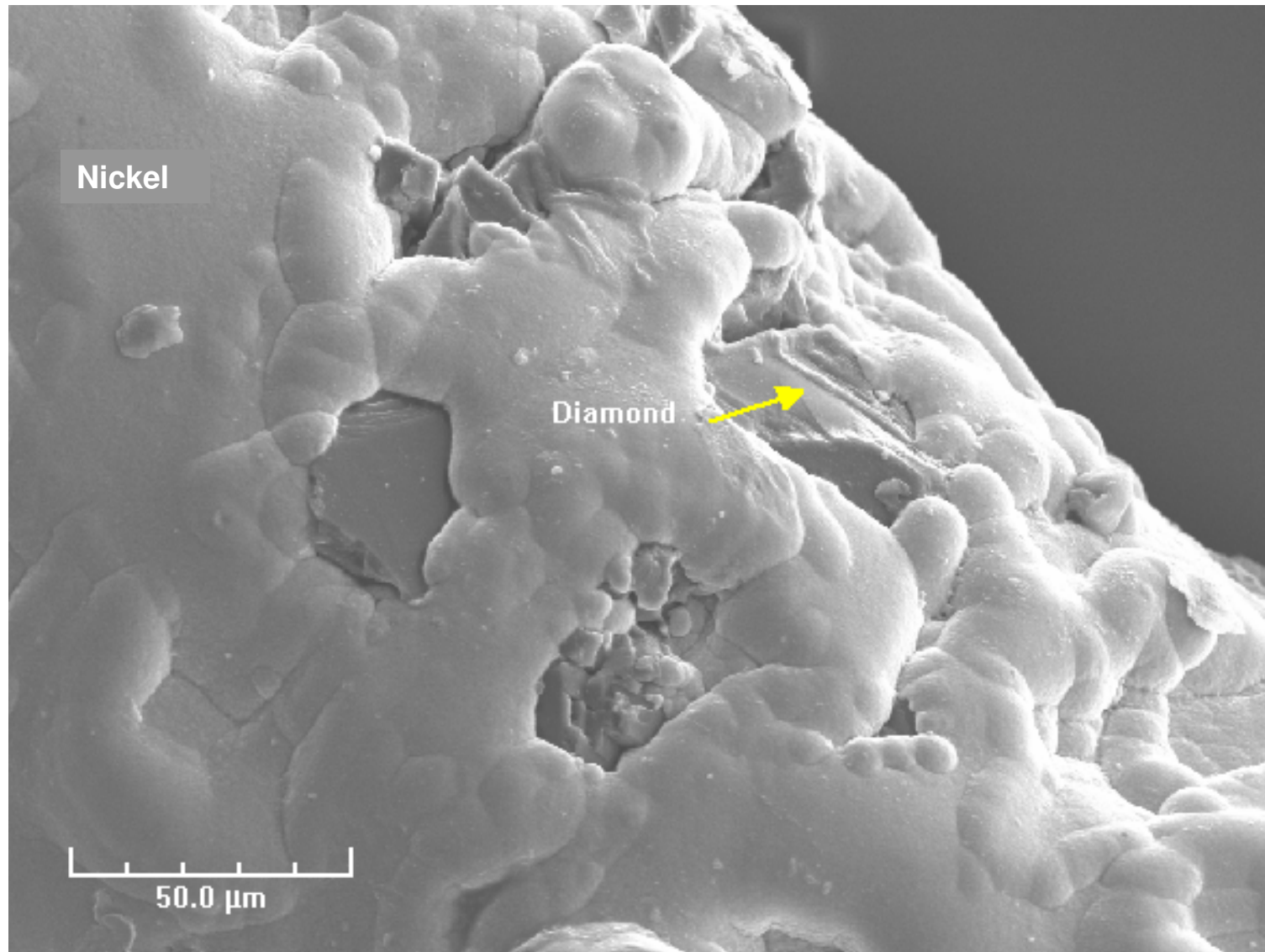


# Diamond Wire





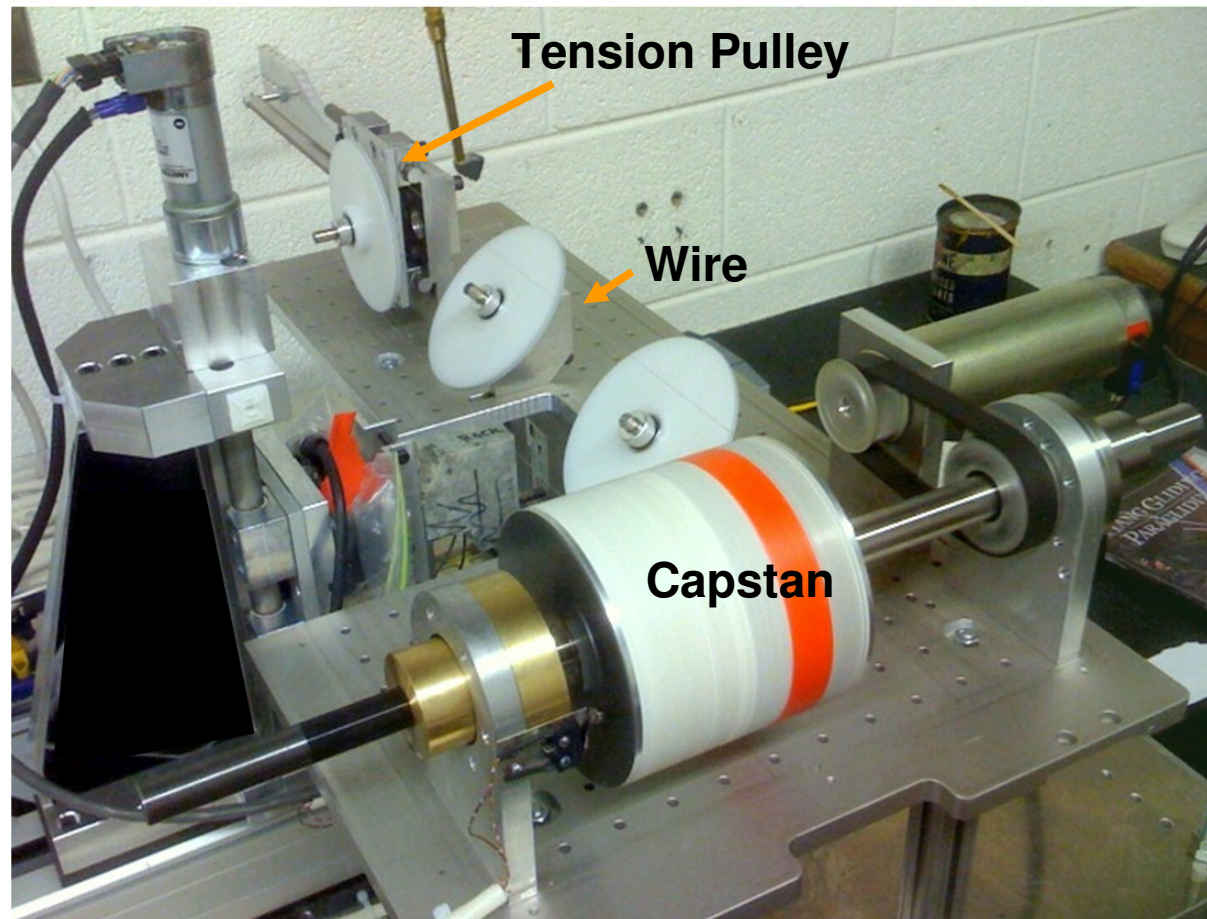
# Diamond Wire



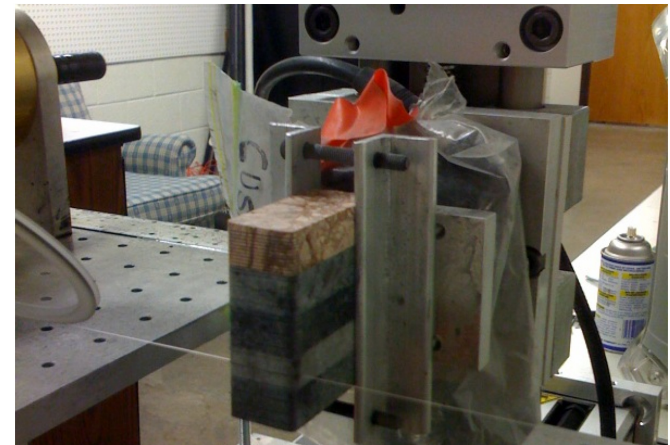
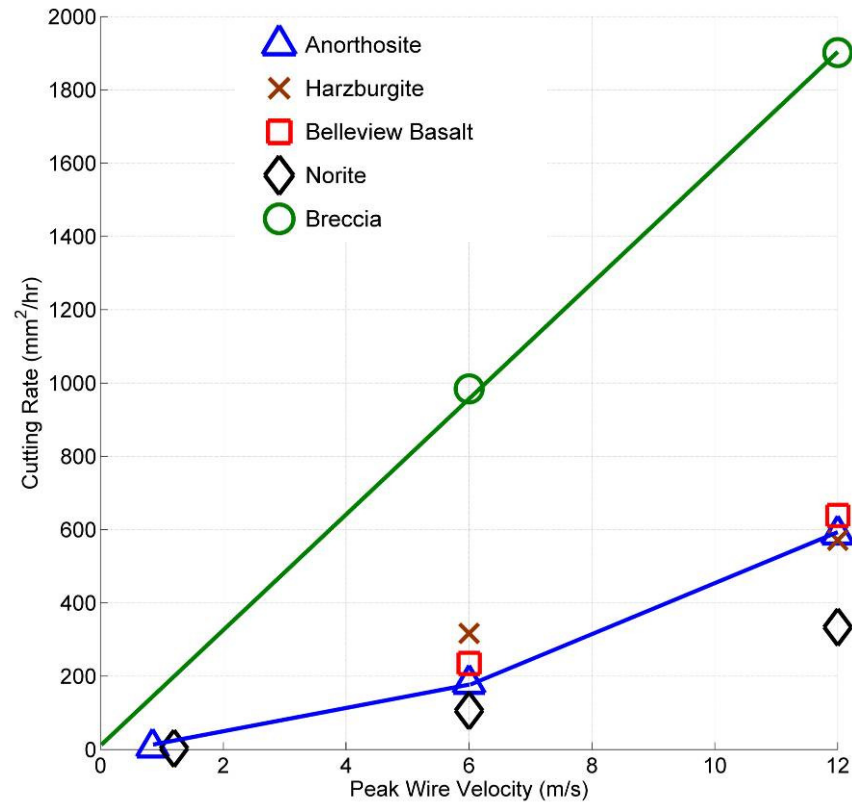
# Diamond Wire Saw Testbed

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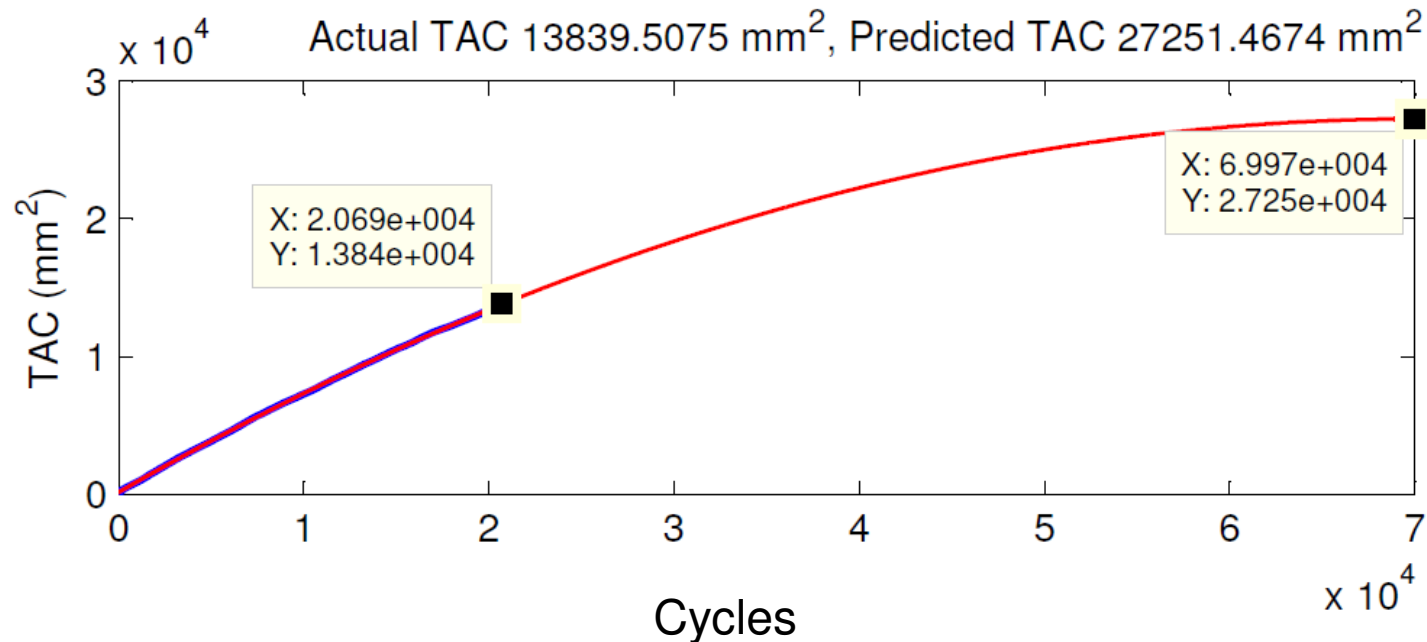
Developed 4 test beds in total. Final was a capstan design.



# Diamond Wire Saw Test Results



# Wire Lifetime test: total area cut (TAC)



- 35m of wire
- Anorthosite
- 12m/s peak linear velocity



# Cutting odd shapes



## Gripping odd shapes



# Fine grinder and polisher - Concepts



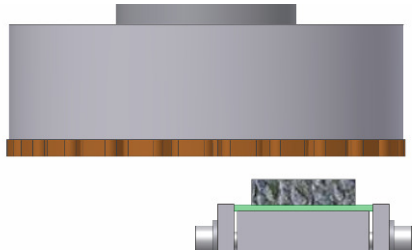
**HONEYBEE** ROBOTICS

## Surface Grinder

- Testing Concepts
  - Surface Grinder

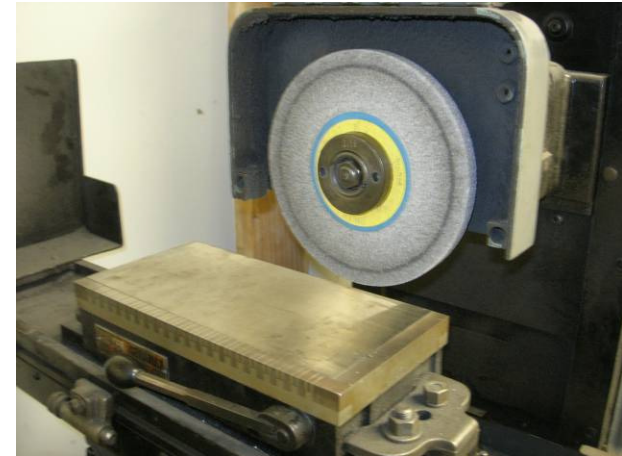
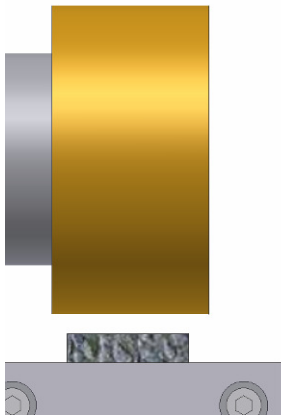
- Plunge Grinding

- Electroplated Diamond
    - Resin Bond with Synthetic Diamond



- Side Grinding

- Resin Bond with Synthetic Diamond
    - Resin Bond with Cubic Boron Nitride (CBN)

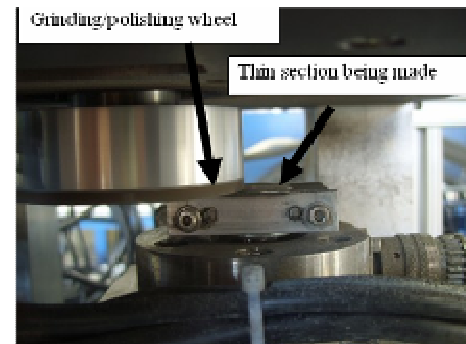
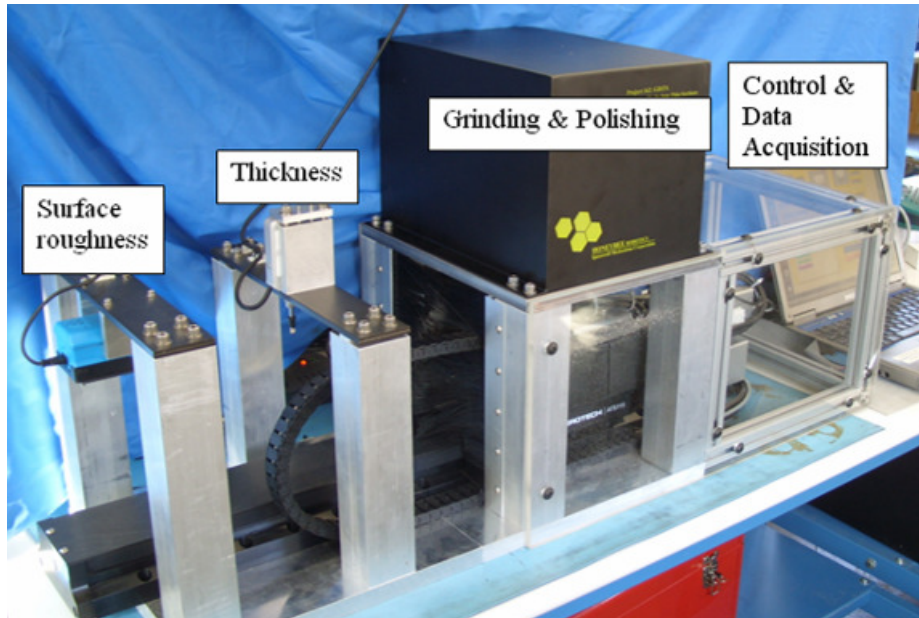


## COTS Grinding Wheels



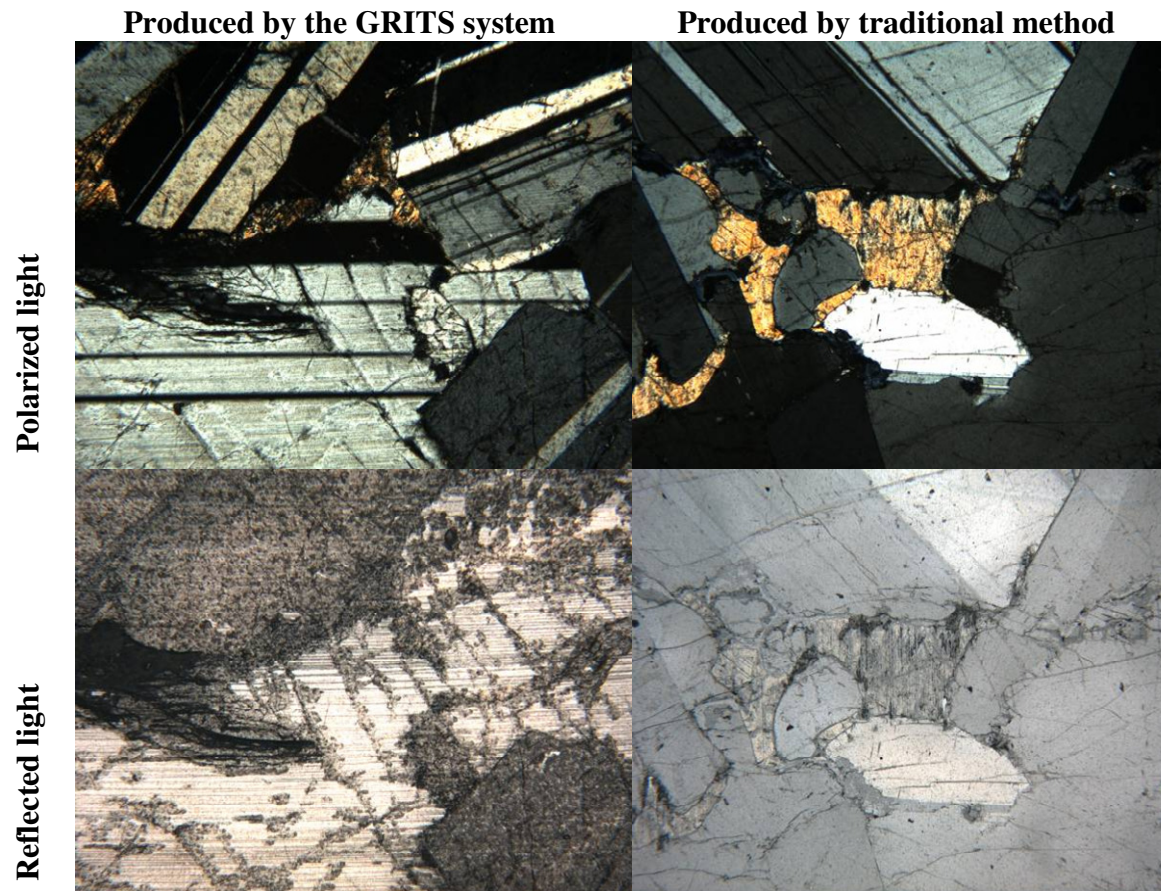
# Fine grinder and polisher – Testbed

## GRITS: Grinding Rocks Into Thin Sections





# GRITS Test Results



Anorthosite

0.2 to 0.3 mm/hr grind rate

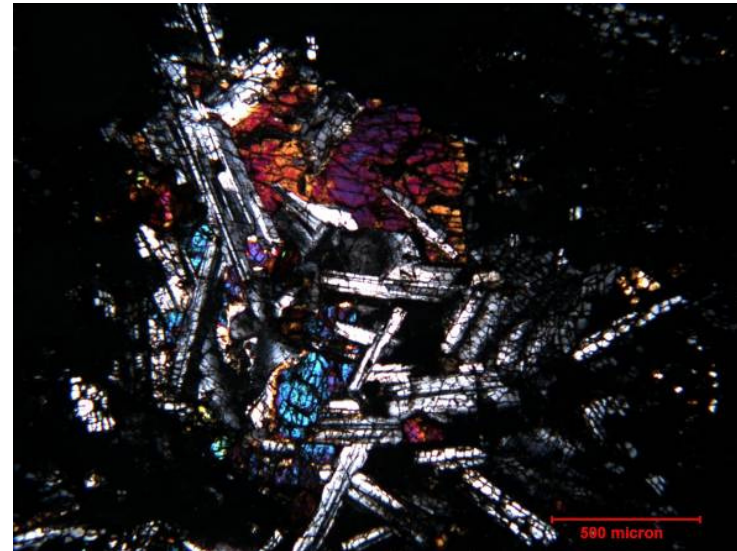
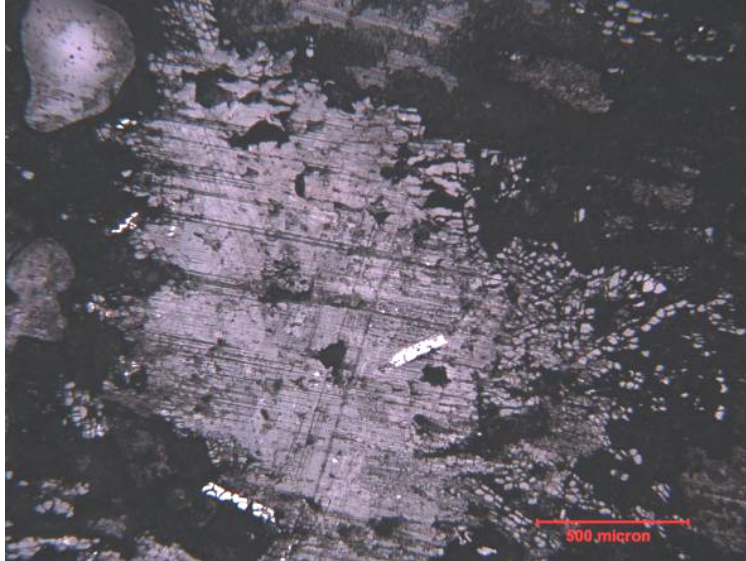
G-ratio  $\sim 13$  (volume rock removed)/(volume grinder lost)

Traditional mount with epoxy on a microscope slide



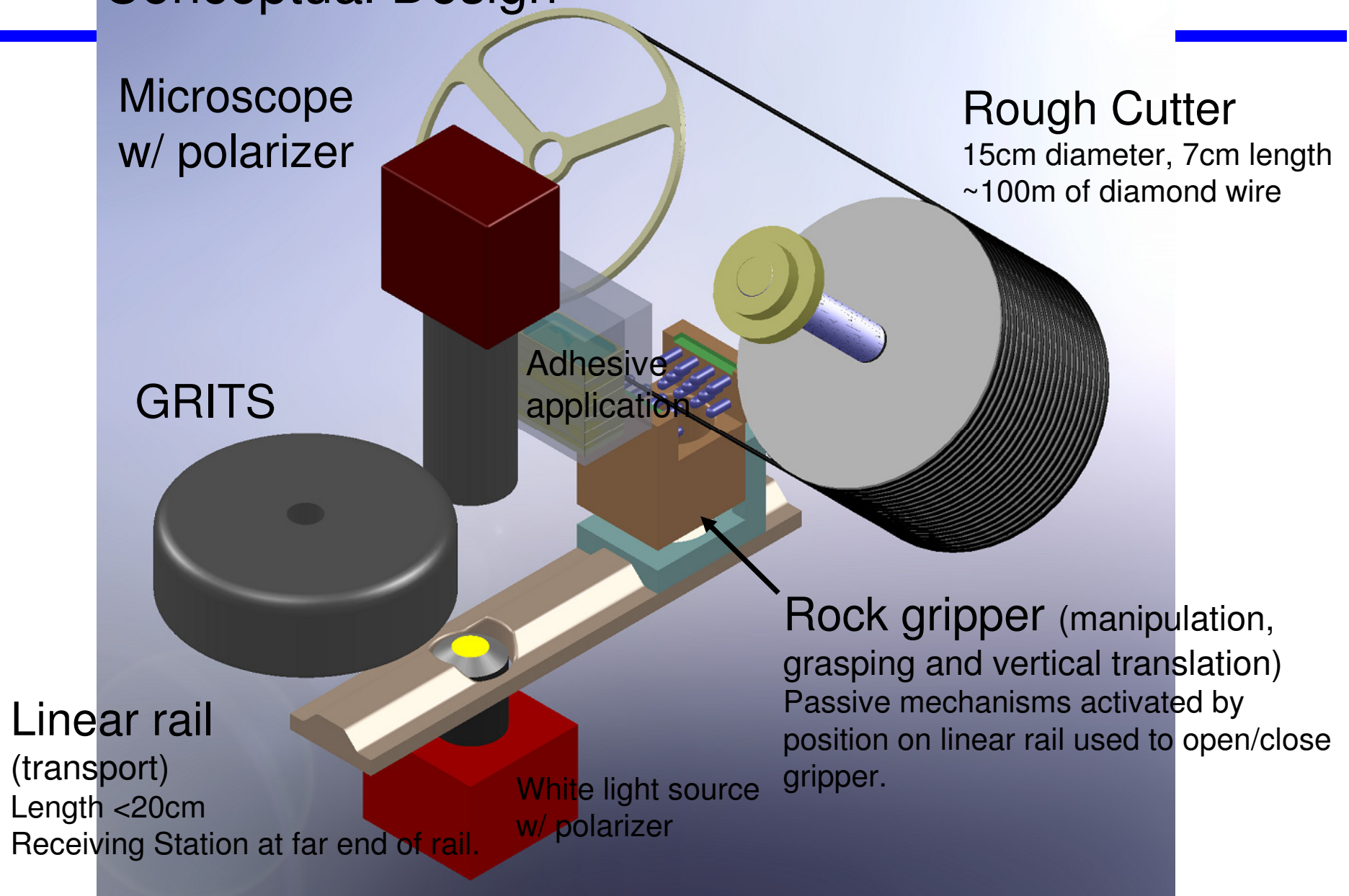
# GRITS Test Results

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Saddleback Basalt (Mars Mojave Simulant Rock)  
0.2 to 0.3 mm/hr grind rate  
G-ratio  $\sim 6$  (volume rock removed)/(volume grinder lost)  
Sample cut by CSM Diamond Wire Saw  
Traditional mount with epoxy on a microscope slide

# Conceptual Design



# Performance estimates, mass, power...

- Produce 50 thin sections of samples of ~3cm basaltic rock, 1cm cores and dust/soil.
- Several days to process one thin section
- Autonomous steps with remote verification and analysis
- Motor count: 3 + clutch or 4
- ~100 meters of wire, GRITS thickness ~1 cm

## Educated estimates of a finished flight system...

Item	Basis	Mass (kg)	Item Power (W)	Power (W) during a sustained operation				
				Cutt ing	Grind/ polish	Imag ing	Manipul ation	Verific ation
GRITS	TRL4 Device, RAT	3	Power is listed with the combined motor item					
GRITS/Wire Cutter Shared Motor	TRL4 Device, RAT	1.2	7 to 10	7	15			
Microscope	MAHLI [17]	0.7	5			5		
Epoxy/Slide	TRL3 JPL ISPAD	0.5	0					
Wire Cutter	TRL4 Device	1.5	Power is listed with the combined motor item					
Linear Rail	Estimate	1.0	3	3			3	
Gripper and Vertical Translation	Estimate	0.5	3				3	
Engineering Camera	Estimate	0.2	2					2
Structural system, housing etc.	Estimate	3						
Electronics	Estimate	3						
<b>Total</b>		<b>14.6</b>		<b>10</b>	<b>15</b>	<b>5</b>	<b>6</b>	<b>2</b>

Number of sections that can be produced is very dependent on mechanical properties of samples → NEED GOOD ANALOG SAMPLES

# Conclusions

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- Have shown a completely dry method to make thin sections
- Have shown that an *in situ* thin section instrument is possible for near term missions.
- Number of sections that can be produced is very dependent on mechanical properties of samples → NEED GOOD ANALOG SAMPLES
- Next step:  
Develop a completely automated system to TRL 6

# Acknowledgements

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